

Amendments to the Claims:

The following listing of claims will replace all prior versions, and listings, of claims in the application:

1. (Currently Amended) A ~~control handle for~~ manipulator intended to control at least one electrohydraulic device, ~~particularly in particular for an item of a~~ public works ~~machinery appliance~~, comprising:

a control handle intended to be manipulated by an operator, including:
— a casing which inwardly delimits a cavity within it,
— at least one set point generator comprising including generator
~~means to deliver for outputting a set point signal~~ set-point signal, and which are situated in the cavity of the casing, and cursor-forming means which are situated on the surface of the casing and which are ~~intended to be~~ actuated by ~~an the~~ operator, the value of the ~~delivered set point~~ output set-point signal being ~~relative~~ related to the ~~movement~~ displacement of the cursor-forming means ~~to control for~~ controlling the electrohydraulic device,

an electronic power board which increases the power of the set-point signal that is output by the set-point generator, said board converting the set point signal into a power signal, the power of which is intended to be output to the electrohydraulic device,

characterized in that

the manipulator is hydraulic,

the handle also comprises a power-electronic circuit ~~power board~~
~~which is integrated into the cavity of the casing of the handle, this circuit board converting the set point signal into a power signal whose power is greater than the power of the set point signal and which is intended to be delivered to the electrohydraulic device and~~

the electronic power board outputs the power signal through a power cable leaving the handle, which extends from the casing in the direction of the

electrohydraulic device, the power signal leaving the handle through the power cable being capable of being used directly for controlling the electrohydraulic device situated downstream.

2. (Currently Amended) The ~~control handle~~manipulator as claimed in claim 1, ~~characterized in that~~wherein the ~~movement~~displacement of the cursor-forming means of the set point generator is independent of the movement of the handle.

3. (Currently Amended) The ~~control handle~~manipulator as claimed in claim 1, ~~characterized in that~~wherein the ~~movement~~displacement of the cursor-forming means is linear.

4. (Currently Amended) The ~~control handle~~manipulator as claimed in claim 1, ~~characterized in that~~wherein the ~~movement~~displacement of the cursor-forming means is rotary.

5. (Currently Amended) The ~~control handle~~manipulator as claimed in claim 1, ~~characterized in that~~wherein the value of the set point signal is proportional to the ~~movement~~displacement of the cursor-forming means.

6. (Currently Amended) The ~~control handle~~manipulator as claimed in claim 1, ~~characterized in that~~wherein the electrohydraulic device comprises a ~~pressure reducer~~pressure-reducing valve.

7. (Currently Amended) The ~~control handle~~manipulator as claimed in claim 1, ~~characterized in that~~wherein the power signal ~~delivered~~that is output by the handle is of the pulse width modulation type.

8. (Currently Amended) The ~~control handle~~manipulator as claimed in claim 1, ~~characterized in that~~wherein the power signal ~~delivered~~that is output by the handle is of the prescribed superposition type.

9. (Currently Amended) The ~~control handle~~manipulator as claimed in claim 1,
~~characterized in that~~wherein the power signal is delivered directly to the electrohydraulic
device.